# Fast computational method for wave scattering 

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# Introduction 

Wave scattering in layered Media Boundary integral equation for Helmholtz equation in 2-D Volume integral equation for Maxwell's equations in 3-D

Fast Solver - Heterogenous Fast Multipole Method

Conclusion

## Boundary value problem



## Boundary value problem

Helmholtz equations

$$
\begin{aligned}
& \Delta u_{1}+k_{1}^{2} u_{1}=0 \\
& \Delta u_{2}+k_{2}^{2} u_{2}=0
\end{aligned}
$$



## Boundary value problem

Helmholtz equations

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\begin{aligned}
& \Delta u_{1}+k_{1}^{2} u_{1}=0 \\
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\end{aligned}
$$

Interface conditions on $\partial \Omega$

$$
\begin{aligned}
u_{1}+u^{i n c} & =u_{2} \\
\frac{\partial u_{1}}{\partial \mathbf{n}}+\frac{\partial u^{i n c}}{\partial \mathbf{n}} & =\frac{\partial u_{2}}{\partial \mathbf{n}}
\end{aligned}
$$



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\end{aligned}
$$

Sommerfeld radiation condition


$$
\lim _{r \rightarrow \infty} \sqrt{r}\left(\frac{\partial u_{1}}{\partial r}-\imath k_{1} u_{1}\right)=0
$$

## Boundary integral equation



## Boundary integral equation

- Solutions in $\mathbb{R}^{2} \backslash \Omega$ and $\Omega$ (Potential theory)



## Boundary integral equation

- Solutions in $\mathbb{R}^{2} \backslash \Omega$ and $\Omega$ (Potential theory)

$u_{1}(\mathbf{r})=\int_{\partial \Omega} \frac{\partial G^{1}}{\partial \mathbf{n}^{\prime}}\left(\mathbf{r}, \mathbf{r}^{\prime}\right) \tau\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}}^{\prime}+\int_{\partial \Omega} G^{1}\left(\mathbf{r}, \mathbf{r}^{\prime}\right) \sigma\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}}^{\prime} \quad$ for $\mathbf{r} \in \mathbb{R}^{2} \backslash \Omega$
$u_{2}(\mathbf{r})=\int_{\partial \Omega} \frac{\partial G^{2}}{\partial \mathbf{n}^{\prime}}\left(\mathbf{r}, \mathbf{r}^{\prime}\right) \tau\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}}^{\prime}+\int_{\partial \Omega} G^{2}\left(\mathbf{r}, \mathbf{r}^{\prime}\right) \sigma\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}}^{\prime} \quad$ for $\mathbf{r} \in \Omega$,
where

$$
G^{i}\left(\mathbf{r}, \mathbf{r}^{\prime}\right)=\frac{\imath}{4} \underbrace{H_{0}^{(1)}\left(k_{i}\left|\mathbf{r}-\mathbf{r}^{\prime}\right|\right)}_{\text {Hankel function }}
$$

## Boundary integral equation

- Solutions in $\mathbb{R}^{2} \backslash \Omega$ and $\Omega$


$$
\begin{array}{ll}
u_{1}(\mathbf{r})=\left(D^{1} \tau\right)(\mathbf{r})+\left(S^{1} \sigma\right)(\mathbf{r}) & \text { for } \mathbf{r} \in \mathbb{R}^{2} \backslash \Omega, \\
u_{2}(\mathbf{r})=\left(D^{2} \tau\right)(\mathbf{r})+\left(S^{2} \sigma\right)(\mathbf{r}) & \text { for } \mathbf{r} \in \Omega,
\end{array}
$$

where

$$
\begin{aligned}
& \left(D^{i} \tau\right)(\mathbf{r})=\int_{\partial \Omega} \frac{\partial G^{i}}{\partial \mathbf{n}^{\prime}}\left(\mathbf{r}, \mathbf{r}^{\prime}\right) \tau\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}}^{\prime} \\
& \left(S^{i} \sigma\right)(\mathbf{r})=\int_{\partial \Omega} G^{i}\left(\mathbf{r}, \mathbf{r}^{\prime}\right) \sigma\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}}^{\prime}
\end{aligned}
$$

## Boundary integral equation

- Matching interface conditions on $\partial \Omega$



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- Let $\mathbf{r} \rightarrow \mathbf{x} \in \partial \Omega$



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- Matching interface conditions on $\partial \Omega$
- Let $\mathbf{r} \rightarrow \mathbf{x} \in \partial \Omega$


$$
\begin{aligned}
& u_{1}(\mathbf{x})=\frac{1}{2} \tau(\mathbf{x})+\left(D^{1} \tau\right)(\mathbf{x})+\left(S^{1} \sigma\right)(\mathbf{x}) \\
& u_{2}(\mathbf{x})=-\frac{1}{2} \tau(\mathbf{x})+\left(D^{2} \tau\right)(\mathbf{x})+\left(S^{2} \sigma\right)(\mathbf{x})
\end{aligned}
$$

## Boundary integral equation

- Matching interface conditions on $\partial \Omega$
- Let $\mathbf{r} \rightarrow \mathbf{x} \in \partial \Omega$


$$
\begin{aligned}
u_{1}(\mathbf{x}) & =\frac{1}{2} \tau(\mathbf{x})+\left(D^{1} \tau\right)(\mathbf{x})+\left(S^{1} \sigma\right)(\mathbf{x}) \\
u_{2}(\mathbf{x}) & =-\frac{1}{2} \tau(\mathbf{x})+\left(D^{2} \tau\right)(\mathbf{x})+\left(S^{2} \sigma\right)(\mathbf{x}) \\
\frac{\partial u_{1}}{\partial \mathbf{n}}(\mathbf{x}) & =\frac{\partial}{\partial \mathbf{n}}\left(D^{1} \tau\right)(\mathbf{x})-\frac{1}{2} \sigma(\mathbf{x})+\frac{\partial}{\partial \mathbf{n}}\left(S^{1} \sigma\right)(\mathbf{x}) \\
\frac{\partial u_{2}}{\partial \mathbf{n}}(\mathbf{x}) & =\frac{\partial}{\partial \mathbf{n}}\left(D^{2} \tau\right)(\mathbf{x})+\frac{1}{2} \sigma(\mathbf{x})+\frac{\partial}{\partial \mathbf{n}}\left(S^{2} \sigma\right)(\mathbf{x})
\end{aligned}
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\frac{\partial u_{1}}{\partial \mathbf{n}}(\mathbf{x}) & =\left(T^{1} \tau\right)(\mathbf{x})-\frac{1}{2} \sigma(\mathbf{x})+\left(D^{1, *} \sigma\right)(\mathbf{x}) \\
\frac{\partial u_{2}}{\partial \mathbf{n}}(\mathbf{x}) & =\left(T^{2} \tau\right)(\mathbf{x})+\frac{1}{2} \sigma(\mathbf{x})+\left(D^{2, *} \sigma\right)(\mathbf{x})
\end{aligned}
$$

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## Boundary integral equation

- Interface Conditions on $\partial \Omega$

$$
\begin{gathered}
\underline{u_{1}}+u^{i n c}=\underline{u_{2}} \\
\frac{\partial u_{1}}{\partial \mathbf{n}}+\frac{\partial u^{i n c}}{\partial \mathbf{n}}=\underline{\frac{\partial u_{2}}{\partial \mathbf{n}}}
\end{gathered}
$$

## Boundary integral equation

- Interface Conditions on $\partial \Omega$

$$
\begin{aligned}
\frac{1}{2} \tau+D^{1} \tau+S^{1} \sigma+u^{i n c} & =-\frac{1}{2} \tau+D^{2} \tau+S^{2} \sigma \\
T^{1} \tau-\frac{1}{2} \sigma+D^{1, *} \sigma+\frac{\partial u^{i n c}}{\partial \mathbf{n}} & =T^{2} \tau+\frac{1}{2} \sigma+D^{2, *} \sigma
\end{aligned}
$$

## Boundary integral equations

- Boundary integral equations (Müller '69, Rokhlin '83)

$$
\begin{aligned}
\tau+\left(D^{1}-D^{2}\right) \tau+\left(S^{1}-S^{2}\right) \sigma & =-u^{i n c} \\
-\sigma+\left(T^{1}-T^{2}\right) \tau+\left(D^{1, *}-D^{2, *}\right) \sigma & =-\frac{\partial u^{i n c}}{\partial \mathbf{n}}
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\end{aligned}
$$

or

$$
\left(\left[\begin{array}{ll}
I & 0 \\
0 & I
\end{array}\right]+\left[\begin{array}{cc}
D^{1}-D^{2} & S^{2}-S^{1} \\
T^{1}-T^{2} & D^{2, *}-D^{1, *}
\end{array}\right]\right)\left[\begin{array}{c}
\tau \\
-\sigma
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\tau \\
-\sigma
\end{array}\right]=\left[\begin{array}{c}
-u^{\text {inc }} \\
-\frac{\partial u^{i n c}}{\partial \mathbf{n}}
\end{array}\right]
$$

- Discretization

$$
(I+A) \boldsymbol{\eta}=\mathbf{f}
$$

- Smooth-star domain : $\omega=4 \pi, \varepsilon_{1}=1, \varepsilon_{2}=4, \mu_{1}=\mu_{2}=1$, $\theta^{i n c}=-\pi / 4,400 \times 400$ matrix and 12-digit accuracy

Incident field


- Smooth-star domain : $\omega=4 \pi, \varepsilon_{1}=1, \varepsilon_{2}=4, \mu_{1}=\mu_{2}=1$, $\theta^{\text {inc }}=-\pi / 4,400 \times 400$ matrix and 12-digit accuracy


## Total field



## Wave scattering in layered Media

Fast computational method for wave scattering
LWave scattering in layered Media

## Layered media



# Two layers with one periodic interface $($ period $=d$ ) 



# Two layers with one periodic interface $($ period $=d)$ 


$\left\llcorner_{\text {Wave scattering in layered Media }}\right.$

- Boundary integral equation for Helmholtz equation in 2-D


## Two layers with one periodic interface $($ period $=d)$



## Fast computational method for wave scattering

LWave scattering in layered Media

- Boundary integral equation for Helmholtz equation in 2-D


## Solution in each layer



LWave scattering in layered Media

- Boundary integral equation for Helmholtz equation in 2-D


## Solution in each layer



$$
\begin{aligned}
& u_{1}(\mathbf{r})=\tilde{D}_{\Omega_{1}}^{1} \tau+\tilde{S}_{\Omega_{1}}^{1} \sigma+\sum_{p=1}^{P} c_{p}^{1} \phi_{p}^{1} \\
& u_{2}(\mathbf{r})=\tilde{D}_{\Omega_{2}}^{2} \tau+\tilde{S}_{\Omega_{2}}^{2} \sigma+\sum_{p=1}^{P} c_{p}^{2} \phi_{p}^{2}
\end{aligned}
$$

## Solution in each layer



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\begin{aligned}
& u_{1}(\mathbf{r})=\tilde{D}_{\Omega_{1}}^{1} \tau+\tilde{S}_{\Omega_{1}}^{1} \sigma+\sum_{p=1}^{P} c_{p}^{1} \phi_{p}^{1} \\
& u_{2}(\mathbf{r})=\tilde{D}_{\Omega_{2}}^{2} \tau+\tilde{S}_{\Omega_{2}}^{2} \sigma+\sum_{p=1}^{P} c_{p}^{2} \phi_{p}^{2}
\end{aligned}
$$

where

$$
\begin{aligned}
&\left(\tilde{D}_{V}^{i} \tau\right)(\mathbf{r}):= \sum_{l=-1}^{1} \alpha^{\prime} \int_{W} \frac{\partial G^{i}}{\partial \mathbf{n}^{\prime}}\left(\mathbf{r}, \mathbf{r}^{\prime}+l \mathbf{d}\right) \tau\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}^{\prime}},\left(\tilde{S}_{V}^{i} \sigma\right)(\mathbf{r}):=\sum_{l=-1}^{1} \alpha^{\prime} \int_{W} G^{i}\left(\mathbf{r}, \mathbf{r}^{\prime}+/ \mathbf{d}\right) \sigma\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}^{\prime}}, \\
&\left(\tilde{T}_{V}^{i} \tau\right)(\mathbf{r}):=\sum_{l=-1}^{1} \alpha^{\prime} \int_{W} \frac{\partial^{2} G^{i}}{\partial \mathbf{n} \partial \mathbf{n}^{\prime}}\left(\mathbf{r}, \mathbf{r}^{\prime}+l \mathbf{d}\right) \tau\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}^{\prime}},\left(\tilde{D}_{V}^{i, *} \sigma\right)(\mathbf{r}):=\sum_{l=-1}^{1} \alpha^{\prime} \int_{W} \frac{\partial G^{i}}{\partial \mathbf{n}}\left(\mathbf{r}, \mathbf{r}^{\prime}+/ \mathbf{d}\right) \sigma\left(\mathbf{r}^{\prime}\right) d s_{\mathbf{r}^{\prime}} . \\
& \phi_{p}^{i}(\mathbf{r}):=\frac{\partial G^{i}}{\partial \mathbf{n}_{p}}\left(\mathbf{r}, \mathbf{y}_{p}^{i}\right)+i k_{i} G^{i}\left(\mathbf{r}, \mathbf{y}_{p}^{i}\right), \mathbf{r} \in \Omega_{i}, p=1,2, \alpha=e^{i d k_{1} \cos \theta^{i n c}}
\end{aligned}
$$

## Boundary integral equations



$$
\begin{aligned}
& u_{1}(\mathbf{r})=\tilde{D}_{\Omega_{1}}^{1} \tau+\tilde{S}_{\Omega_{1}}^{1} \sigma+\sum_{p=1}^{P} c_{p}^{1} \phi_{p}^{1} \\
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\end{aligned}
$$

- Interface conditions


## Boundary integral equations



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\end{aligned}
$$

- Interface conditions
- Quasi-periodicity

$$
\begin{aligned}
& \left.u\right|_{L}-\left.\alpha u\right|_{R}=0 \\
& \left.u_{n}\right|_{L}-\left.\alpha u_{n}\right|_{R}=0
\end{aligned}
$$

## Boundary integral equations



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\begin{aligned}
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\end{aligned}
$$

- Interface conditions
- Quasi-periodicity
$\left.u\right|_{L}-\left.\alpha u\right|_{R}=0$
$\left.u_{n}\right|_{L}-\left.\alpha u_{n}\right|_{R}=0$
- Radiation condition
(Rayleigh-Bloch Expansion)


## Boundary integral equations



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- Quasi-periodicity

$$
\begin{aligned}
& \text { - Quasi-periodicity } \\
& \left.u\right|_{L}-\left.\alpha u\right|_{R}=0 \\
& \left.u_{n}\right|_{L}-\left.\alpha u_{n}\right|_{R}=0
\end{aligned} \quad \rightarrow\left[\begin{array}{ccc}
\mathbf{A} & \mathbf{B} & \mathbf{0} \\
\mathbf{C} & \mathbf{Q} & \mathbf{0} \\
\mathbf{Z} & \mathbf{V} & \mathbf{W}
\end{array}\right]\left[\begin{array}{c}
\boldsymbol{\eta} \\
\mathbf{c} \\
\mathbf{a}
\end{array}\right]=\left[\begin{array}{l}
\mathbf{f} \\
\mathbf{0} \\
\mathbf{0}
\end{array}\right]
$$

- Radiation condition (Rayleigh-Bloch Expansion)

LWave scattering in layered Media

- Flat surface $\left(\varepsilon_{1}=1, \varepsilon_{2}=1.77\right.$ (water), $\omega=30$, Error $=2 \times 10^{-14}$ )


LWave scattering in layered Media

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Reflected+Transmitted wave


- Flat surface $\left(\varepsilon_{1}=1, \varepsilon_{2}=1.77\right.$ (water), $\omega=30$, Error $\left.=2 \times 10^{-14}\right)$


## Total field



- Sine surface ( $\varepsilon_{1}=1, \varepsilon_{2}=1.77$ (water), $\omega=30$, Error $=5 \times 10^{-13}$ )


LWave scattering in layered Media

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Reflected+Transmitted wave


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## Total field



- In 2-D, boundary integral equation methods using periodizing scheme
$\rightarrow$ Left : J. Lai, M. Kobayashi, A. Barnett, JCP 2015 $\rightarrow$ Right : (1000 layers) M.H. Cho and A. Barnett OPEX 2015

- CPU time and memory usage

| Number of interfaces | 1 | 3 | 10 | 30 | 100 | 300 | 1000 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Matrix Filling (sec) | 0.518 | 1.860 | 4.200 | 5.600 | 12.384 | 32.332 | 103.331 |
| Schur Complement (sec) | 0.028 | 0.058 | 0.299 | 0.644 | 2.263 | 6.525 | 21.037 |
| Block Solve (sec) | 0.003 | 0.041 | 0.398 | 0.898 | 2.805 | 8.626 | 26.655 |
| Memory (MB) | 18 | 41 | 83 | 183 | 608 | 1753 | 5830 |
| Flux Error | $4.8 \mathrm{e}-12$ | $3.1 \mathrm{e}-11$ | $2.4 \mathrm{e}-11$ | $4.0 \mathrm{e}-11$ | $2.2 \mathrm{e}-11$ | $1.3 \mathrm{e}-10$ | $9.1 \mathrm{e}-10$ |

- In 3-D, BIE for Maxwell's equations is challenging

- In 3-D, BIE for Maxwell's equations is challenging
$\rightarrow$ Lippmann-Schwinger type volume integral equation (VIE)
(D. Chen, W. Cai, B. Ziner, and M.H. Cho, JCP, 2016)

$$
\mathbf{C} \cdot \mathbf{E}(\mathbf{r})=\mathbf{E}^{i n c}(\mathbf{r})-\imath \omega \mu(\mathbf{r}) \int_{\Omega} d \mathbf{r}^{\prime} \imath \omega \Delta \varepsilon\left(\mathbf{r}^{\prime}\right) \cdot \overline{\mathbf{G}}_{E}\left(\mathbf{r}^{\prime}, \mathbf{r}\right)
$$

where

$$
\mathbf{C}=\mathbf{I}+\mathbf{L}_{V_{\delta}} \cdot \Delta \varepsilon(\mathbf{r})
$$

and the Dyadic Green's function

$$
\overline{\mathbf{G}}_{E}=\frac{1}{4 \pi}\left(\mathbf{I}+\frac{1}{k^{2}} \nabla \nabla\right) \frac{e^{-\imath k\left|\mathbf{r}-\mathbf{r}^{\prime}\right|}}{\left|\mathbf{r}-\mathbf{r}^{\prime}\right|}
$$



Fast computational method for wave scattering
LWave scattering in layered Media

- Volume integral equation for Maxwell's equations in 3-D


Fast computational method for wave scattering
LWave scattering in layered Media

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LWave scattering in layered Media

- Volume integral equation for Maxwell's equations in 3-D
- Lippmann-Schwinger type Volume integral equation in multilayered media

- Lippmann-Schwinger type Volume integral equation in multilayered media

- Dyadic Green's function $\overline{\mathbf{G}}_{E} \rightarrow$ Layered media Dyadic Green's function $\overline{\mathbf{G}}_{E}^{L}$
- Layered media Green's function using Sommerfeld integrals and Fresnel reflection coefficients (M.H. Cho and W. Cai, JSC 2017)


## Fast computational method for wave scattering

L Wave scattering in layered Media

- Volume integral equation for Maxwell's equations in 3-D
- Reflected parts $(j=1,2)$

$$
\begin{aligned}
& G_{j x x}^{R}=k_{j}^{2} g_{j, 1}^{R}-\frac{1}{2}\left(g_{j, 3}^{R}+g_{j, 7}^{R}\right)+\left(\frac{1}{2} \rho^{2}-\left(y-y^{\prime}\right)^{2}\right) g_{j, 2}^{R} \\
& G_{j y y}^{R}=k_{j}^{2} g_{j, 1}^{R}-\frac{1}{2}\left(g_{j, 3}^{R}+g_{j, 7}^{R}\right)+\left(\frac{1}{2} \rho^{2}-\left(x-x^{\prime}\right)^{2}\right) g_{j, 2}^{R} \\
& G_{j z z}^{R}=-g_{j, 3}^{R} \\
& G_{j x y}^{R}=G_{j y x}^{R}=\left(x-x^{\prime}\right)\left(y-y^{\prime}\right) g_{j, 2}^{R} \\
& G_{j x z}^{R}=-G_{j z x}^{R}=-i\left(x-x^{\prime}\right) g_{j, 6}^{R}, G_{j y z}^{R}=-G_{j z y}^{R}=-i\left(y-y^{\prime}\right) g_{j, 6}^{R}
\end{aligned}
$$

- Transmitted parts $(j=2,3)$

$$
\begin{aligned}
& G_{j x x}^{T}=k_{j}^{2} g_{j, 1}^{T}-\frac{1}{2} g_{j, 3}^{T}+\left(\frac{1}{2} \rho^{2}-\left(y-y^{\prime}\right)^{2}\right) g_{j, 2}^{T} \\
& G_{j y y}^{T}=k_{j}^{2} g_{j, 1}^{T}-\frac{1}{2} g_{j, 3}^{T}+\left(\frac{1}{2} \rho^{2}-\left(x-x^{\prime}\right)^{2}\right) g_{j, 2}^{T}, \\
& G_{j z z}^{T}=g_{j, 4}^{T}, \\
& G_{j x y}^{T}=G_{j y x}^{T}=\left(x-x^{\prime}\right)\left(y-y^{\prime}\right) g_{j, 2}^{T} \\
& G_{j x z}^{T}=i\left(x-x^{\prime}\right) g_{j, 6}^{T}, G_{j y z}^{T}=i\left(y-y^{\prime}\right) g_{j, 6}^{T} \\
& G_{j z x}^{T}=i\left(x-x^{\prime}\right) g_{j, 9}^{T}, G_{j z y}^{T}=i\left(y-y^{\prime}\right) g_{j, 9}^{T},
\end{aligned}
$$

where

$$
g^{R, T}=2 \pi \int_{0}^{\infty} k_{s}^{n+1} \tilde{g} \frac{J_{n}\left(k_{s} \rho\right)}{\rho^{n}} e^{ \pm \imath k_{z}\left(z+z^{\prime}\right)} d k_{s} \text { and } \tilde{g}=\tilde{g}\left(k_{s}\right)
$$

$\left\llcorner_{\text {Wave scattering in layered Media }}\right.$

- Volume integral equation for Maxwell's equations in 3-D
- Electric field Green's function in a 3 layer structure

- Volume integral equation with layered media Green's function (D. Chen, M.H. Cho, and W. Cai, SISC, 2016 submitted)

$$
\mathbf{C} \cdot \mathbf{E}(\mathbf{r})=\mathbf{E}^{i n c}(\mathbf{r})-\imath \omega \mu(\mathbf{r}) \int_{\Omega} d \mathbf{r}^{\prime} \imath \omega \Delta \varepsilon\left(\mathbf{r}^{\prime}\right) \cdot \overline{\mathbf{G}}_{E}^{L}\left(\mathbf{r}^{\prime}, \mathbf{r}\right)
$$

where

$$
\mathbf{C}=\mathbf{I}+\mathbf{L}_{V_{\delta}} \cdot \Delta \varepsilon(\mathbf{r})
$$

$\left\llcorner_{\text {Wave scattering in layered Media }}\right.$

- Volume integral equation for Maxwell's equations in 3-D
- Volume integral equation with layered media Green's function


Fast solver - Heterogeneous Fast Multipole Method

## Fast Solver

- Fast Multipole Method (FMM) by Rokhlin and Greengard

$$
\sum_{i=1}^{N} G\left(x_{j}, x_{i}\right) q_{i}, \quad j=1,2, \cdots N
$$

$\rightarrow N$-body problem or Matrix vector multiplication

- Direct computation: $\mathcal{O}\left(N^{2}\right)$
- FMM: $\mathcal{O}(N)$ or $\mathcal{O}(N \log N)$


## Fast Solver

- Integral operator for Helmholtz equation in the free-space

$$
u(\mathbf{x})=\int_{\partial \Omega} g\left(\mathbf{x}, \mathbf{x}^{\prime}\right) q\left(\mathbf{x}^{\prime}\right) d \mathbf{x}^{\prime} \approx \sum_{i=1}^{N} g\left(\mathbf{x}, \mathbf{x}_{i}^{\prime}\right) q\left(\mathbf{x}_{i}^{\prime}\right)
$$

where $g\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=\frac{\imath}{4} H_{0}^{(1)}\left(k\left|\mathbf{x}-\mathbf{x}^{\prime}\right|\right)$

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- Graf's Addition Theorem

$$
C_{\nu}(w) e^{\imath \nu \chi}=\sum_{p=-\infty}^{\infty} C_{\nu+p}(u) J_{p}(v) e^{\imath p \alpha}
$$

where $C_{\nu}$ is either $H_{\nu}^{(1)}$ or $J_{\nu}$


- Multipole expansion

$$
u(\mathbf{x})=\sum_{i=1}^{N} \frac{\imath}{4} H_{0}^{(1)}\left(k\left|\mathbf{x}-\mathbf{x}_{i}^{\prime}\right|\right) q\left(\mathbf{x}_{i}^{\prime}\right) \approx \frac{\imath}{4} \sum_{p=-P}^{P} \alpha_{p} H_{p}\left(k\left|\mathbf{x}-\mathbf{x}_{c}\right|\right) e^{\imath p \theta_{c}}
$$

where

$$
\alpha_{p}=\sum_{j=1}^{N} q_{j} e^{-\imath p \theta_{j}} J_{p}\left(k \rho_{j}\right)
$$



- Helmholtz equation with Impedance boundary condition (method of image)

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$$
\begin{aligned}
u_{\mathbf{x}_{0}}(\mathbf{x}) & =g\left(\mathbf{x}, \mathbf{x}_{0}\right)+u_{\mathbf{x}_{0}}^{s}(\mathbf{x}) \\
& \equiv g\left(\mathbf{x}, \mathbf{x}_{0}\right)+\left(g\left(\mathbf{x}, \mathbf{x}_{0}^{i m}\right)+2 \imath \alpha \int_{0}^{\infty} g\left(\mathbf{x}, \mathbf{x}_{0}^{i m}-s \hat{y}\right) e^{\imath \alpha s} d s\right)
\end{aligned}
$$

- $N$ source points

- Multipole expansion

$$
\begin{aligned}
u(\mathbf{x}) & \approx \frac{i}{4} \sum_{p=-P}^{P} \alpha_{p} H_{p}\left(k\left|\mathbf{x}-\mathbf{x}_{c}\right|\right) e^{\imath p \theta_{c}} \\
& +\frac{\imath}{4} \sum_{p=-P}^{P} \bar{\alpha}_{p}\left(H_{p}\left(k\left|\mathbf{x}-\mathbf{x}_{c}^{i m}\right|\right) e^{\imath p \theta_{i m}}\right. \\
& \left.\quad+2 \imath \alpha \int_{0}^{\infty} H_{p}\left(k\left|\mathbf{x}-\left(\mathbf{x}_{c}^{i m}-s \hat{y}\right)\right|\right) e^{\imath p \hat{\theta}_{i m}} e^{\imath \alpha s} d s\right),
\end{aligned}
$$


where $\bar{\alpha}_{p}$ is the complex conjugate of $\alpha_{p}$.

- Test problem (Uniform distribution in a unit box)

- Accuracy for $k=0.1$ and $k=1$ with $N=10000$

| $p$ | Error for $k=0.1$ | Error for $k=1$ |
| :---: | :---: | :---: |
| $E_{5}$ | $1.23 \times 10^{-4}$ | $1.43 \times 10^{-4}$ |
| $E_{10}$ | $2.73 \times 10^{-6}$ | $3.81 \times 10^{-6}$ |
| $E_{20}$ | $2.06 \times 10^{-9}$ | $2.85 \times 10^{-9}$ |
| $E_{30}$ | $1.19 \times 10^{-11}$ | $1.65 \times 10^{-11}$ |

- CPU time for $p=39$ and $k=0.1$ (Intel Xeon E5-2697 2.6Ghz with gcc, Dell 7910 workstation)

| $N$ | 100 | 6400 | 10000 | 90000 | 360000 | 640000 | 810000 | 1000000 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| H-FMM time (sec) | 0.01 | 0.67 | 1.19 | 10.92 | 46.58 | 100.85 | 116.03 | 135.05 |
| Direct time (sec) |  |  | 1.64 | 132.50 | 2199.92 | 6700 | 10732.10 | 16357.42 |

## - CPU time in the log-log scale (linear scaling ©)



## Conclusions and Summary

- Boundary integral equation (BIE) method for layered media
- EM scattering problem using volume integral equation (VIE) method
- Heterogeneous fast multipole method
$\rightarrow$ Extension to multi-layered media (on-going work)
- Stochastic methodology for meta-material design
- Some source codes http://faculty.uml.edu/min_cho/software.html

Thank you!

